

Expressive Talking Avatars

Figure 1: Expressive Talking Avatars: a New Dataset and a New Method

ABSTRACT

Stylized avatars are common virtual representations used in VR to support interaction and communication between remote collaborators. However, explicit expressions are notoriously difficult to create, mainly because most current methods rely on geometric markers and features modeled for human faces, not stylized avatar faces. To cope with the challenge of emotional and expressive generating talking avatars, we build the Emotional Talking Avatar Dataset which is a talking-face video corpus featuring 6 different stylized characters talking with 7 different emotions. Together with the dataset, we also release an emotional talking avatar generation method which enables the manipulation of emotion. We validated the effectiveness of our dataset and our method in generating audio based puppetry examples, including comparisons to state-of-the-art techniques and a user study. Finally, various applications of this method are discussed in the context of animating avatars in VR.

Index Terms: Human-centered computing—Human computer interaction (HCI)—HCI design and evaluation methods—User studies; Human-centered computing—Computer graphics—Graphics systems and interfaces—Virtual reality

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1 INTRODUCTION

Immersive virtual reality (VR) is recognized as a key interaction technology in the future metaverse, where users utilize stylized avatars to represent themselves [29]. However, VR head-mounted displays (HMDs) typically obstruct a significant portion of the user's face [19], limiting the applicability of most existing video-driven facial animation methods. While current audio-driven talking avatar techniques have advanced HMD-based avatar-mediated communication, several challenges persist. Contemporary methods excel in generating lip movements perfectly synchronized with audio speech [30], yet they often overlook facial emotion. Given that facial expressions are a primary nonverbal mode of human communication, addressing this gap is crucial. Some researchers have explored emotional talking face generation methods enabling the manipulation of emotion and intensity; however, these methods are tailored for human faces [32, 35], not stylized character faces.

A significant number of recent advancements in the task of talking avatar generation involve deep learning-based methods [35], where data plays a pivotal role in performance. We contend that the absence of a high-quality dataset for 3D rigs is the primary obstacle to achieving vivid talking avatar generation. As discussed in the next section, available datasets are predominantly developed for human faces rather than stylized characters. Aneja et al. developed stylized character datasets with cardinal expression annotations [1,2]. However, their dataset only includes labeled facial expressions, lacking audio-visual animation clips with mapped lip movements synchronized with audio. To address this gap, we have created the Emotional Talking Avatar Dataset, featuring animations of six avatars speaking with seven different emotions. We meticulously selected emotionally consistent speech texts covering various phonemes from existing audio-visual human datasets. Our in-house professional animator

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crafted animation clips in seven categories, including anger, disgust, fear, joy, neutral, sadness, and surprise.

Together with the dataset, we presented the emotional talking avatars specially designed for 3D stylized characters in a geometrically consistent and perceptually valid way. Our method begins by utilizing a pre-trained HuBERT model to extract features, facilitating the precise generation of rig parameters that control the mouth region's movements. Another emotion branch is introduced for generating emotional displacement to the emotionless lip motions. Through a straightforward fusion process, we create emotionally responsive talking heads that react to both audio input and emotional context.

We validate our dataset and our method by measuring emotional recogonition, intensity, synchronization, & naturalness, which are crucial factors for audience engagement. Our dataset were identified with 72% accuracy, which is comparable to the mean accuracy rates for the human condition (videos taken from MEAD [35] with three intensity levels and RAVDESS [21] with 'normal' and 'strong' intensity level) at 73.9%. Results also show that our method maintained the same level of intensity lip sync quality, & naturalness compared to the human condition. Additionally, results also reveal our talking head generation method significantly improved scores of the lip sync quality & naturalness, while maintaining the same level of expression recognition & intensity compared to SOTA. This research makes several contributions, as follows:

- We build a high-quality dataset of emotional talking avatars, marking the first emotional audio-visual corpus annotated for 3D rigs of stylized characters.
- We propose a new method for generating emotional talking avatars that allows for the manipulation of emotions.
- Extensive experiments validated dataset, and our expressive avatar generation methods could be apply to future reference in AR/VR/XR.

2 RELATED WORK

2.1 3D Avatars in Virtual Reality

Avatars serve as digital representations of users, taking on forms that range from abstract and cartoonish to human-like [39]. These digital entities may embody a user during a video call or function as characters in video games. Depending on the context, avatars can be manually crafted by designers and character artists, as seen in animated movies [18], or generated using computer vision or other techniques to produce a digital 2D or 3D representation resembling a user's visual appearance [23, 24]. Implementation variations allow for diverse levels of customization, encompassing facial features, body type, clothing, and accessories. Avatars can also be animated to enable users to express emotions and establish a sense of self-identification. Typically, this involves rigging a skeletal system [8], manipulated through user sensing and tracking. Achieving this can involve methods such as cameras and computer vision [5], speech sentiment analysis, or animating visemes based on audio input.

We focus our efforts on stylized 3D characters, defined as characters that no human would mistake for another person, but would still be perceived as having human emotions and thought processes. Our goal is to develop an approach for driving stylized character expressions only using sensors from commodity VR hardware as they contain microphones for audio input.

2.2 Audio Driven Facial Animation

Audiovisual speech animation can be categorized into procedural, performance-capture, data-driven, and deep-learning techniques [25,41]. Procedural speech animation utilizes visemes, defining the oral shape at the apex of a given phoneme, to address overlaps between successive visemes. This involves curve shapes that specify the attach, apex, sustain, and decay phases of a viseme, mapping a given phoneme to a corresponding viseme [34]. Performancecapture speech animation is visually limited by the actor's performance, making it challenging for animators to edit or refine [20]. Data-driven approaches seamlessly assemble fragments of facial animation data from a large corpus to synchronize with an input speech track, employing methods such as morphable models [11]. However, these data-driven methods are often constrained by the available data and, similar to performance-capture, may not be animator-centric in their output.

Recent research has shown the potential of deep learning to provide a compelling solution to automatic lip-synchronization simply using an audio signal [3, 32, 36]. Current deep learning based methods can be broadly categorized into 2D methods and 3D methods. For 2D methods, Zhou et al. present a new deep-learning based architecture to predict facial landmarks, capturing both facial expressions and overall head poses, from only speech signals [40]. When it comes to 3D methods which is more related to our task, Taylor et al. employ phonemes as an intermediate speech signal to drive coefficients of an Active Appearance Model, representing the lower face and jaw of a head model [33]. Edwards et al. introduced the JALI model to simulate different speech styles by controlling jaw and lip parameters in a two-dimensional viseme space [10]. Zhou et al. predict sparsely activated viseme- and co-articulation parameters for a FACS-rig from speech, utilizing both phonemes and raw speech features [41].

In particular, Chen et al. devised a text-to-speech (TTS) data augmentation technique for talking face applications. This involves the creation of augmented audio-animation pairs through a TTS system, addressing misalignment challenges associated with TTS audio using the introduced soft-DTW loss mechanism. The weighted sum of HuBERT features is employed to fully harness the underlying information in the audio. Their method has been demonstrated to enhance the few-shot capability of a talking face system in situations with limited data resources [6].

Inspired by the previous work developed for human faces [6], we also utilized the pre-trained HuBERT model [14] as a feature extractor, showcasing consistently superior performance across diverse downstream tasks compared to traditional handcrafted acoustic features like MFCC. This leads to improved lip-synchronization. We further implemented the Soft-DTW loss to effectively address potential data misalignment issues.

2.3 Emotion and Expressiveness

Emotion significantly influences the realism of animation, yet few works address its incorporation in talking face generation due to the challenging nature of capturing emotion dynamics. Karras et al. tackled this by animating 3D vertices of a face based on a speech signal, employing an end-to-end deep network comprising a formant analysis network, an articulation network, and a learned emotion embedding [17].

Wang et al. curated the MEAD dataset and proposed a baseline for emotional talking face generation, allowing manipulation of emotion and intensity. Their two-branch architecture processes audio and emotional conditions separately, with one branch mapping audio to lip movements and the other synthesizing the desired emotion on the target face. Intermediate representations are fused in a refinement network to produce emotional talking-face videos [35]. While MEAD addresses a similar task to our method, we emphasize key differences and superiority. MEAD comprises three sub-networks: an audio-to-landmarks module, a neutral-to-emotion transformer, and a refinement network. This three-stage structure is complex, demanding more computational resources and introducing discontinuity between generated video frames. In contrast, we directly generate rig parameters from audio and emotion labels, providing a "Lot of people will roam the streets in costumes and masks and having a ball" with anger emotion

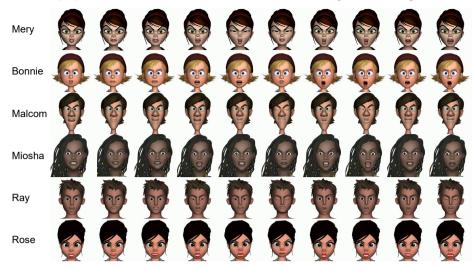


Figure 2: Sampled frames from dataset.

more concise approach. Notably, MEAD is tailored for real human animation, not stylized characters.

Ji et al. propose a method to decompose speech into decoupled content and emotion spaces, synthesizing emotion dynamics from audio [16]. They also introduce the Emotion-Aware Motion Model (EAMM) for generating one-shot emotional talking faces using an emotion source video, demonstrating satisfactory results with realistic emotion patterns on arbitrary subjects [15]. Gururan et al. present SPACE, a system that utilizes speech and a single image to generate high-resolution, expressive videos with realistic head pose, eliminating the need for a driving video [13]. While these methods animate 3D models of faces, such as standard FACS-based photorealistic avatars, others directly animate raw images of human faces but are not specifically developed for 3D stylized characters.

While a reliable parameterization of emotion and expression remains elusive, the ubiquity of the six cardinal expressions in stories and face-to-face interactions makes them a suitable focus for educators and facial expression researchers. To guide and automate the process of expression animation, animators and researchers often turn to FACS. For instance, FACSGen enables the control of action units on realistic 3D synthetic faces. However, the strict adherence to anatomy-based and constrained motion in these systems restricts their generalizability to characters with different anatomies and limits their applications, as the most believable animation may necessitate the violation of physical laws.

Aneja et al. were pioneers in exploring the learning of 3D stylized character expressions from humans in a perceptually valid and geometrically consistent manner. They curated the FERG-DB database, containing labeled facial expressions for six stylized characters, developed in collaboration with facial expression artists and initially labeled via Mechanical Turk (MT). Subsequently, they introduced two systems, DeepExpr and ExprGen. DeepExpr, given a 2D image of a human, retrieves the matching stylized character expression image. On the other hand, ExprGen, when provided with a 2D image of a human, generates the 3D rig parameters for a stylized character.

Built on the FERG-DB database, Pan et al. contributed a performance-based real-time method to animate believable and accurate facial expressions of 3D stylized characters [27]. Additionally, they introduced an audio-based facial animation approach to depict characters in a geometrically consistent and perceptually correct manner. The lips motion are controlled by the contents of the au-

dio, and the facial dynamics are established by category of the emotion and the intensity [26]. However, FERG-DB database is labeled facial expressions of stylized characters, and thus difficult to ensure accurate lip synchronization, while generating realistic motions for the entire face with vivid emotional changes. Additionally, EVP [26] utilizes the audio-to-landmarks module in MAED to predict landmarks which are then matched with the landmarks in the FERG-3D-DB dataset [1], but there are two main problems: a) there are huge domain gaps between the landmarks in such two different datasets, which leads to inaccuracies and error accumulation. b) each frame needs to be be found one by one in more than 10,000 images contained in FERG-3D-DB, which is very time-consuming. By comparison, we utilize our published dataset to perform end-to-end prediction on rig parameters via a simple network, which greatly speeds up the prediction generation efficiency.

To tackle issues discussed above, we contribute a novel emotional audio-visual dataset for stylized character rigs dataset with cardinal expression annotations, and then a novel method to accurately retrieve plausible character expressions from audio input only.

3 DATASET

3.1 Design Criteria

Emotion Categories We utilize seven emotion categories, as defined by Aneja et al. [1, 2] (anger, disgust, fear, joy, sadness, surprise, and neutral). These categories are widely recognized within the facial expression research community due to their consensus, and they encompass a broad range of intensities. Additionally, they can blend with each other to create additional expressions.

Design of the Speech Corpus For audio speech content, we follow the MEAD [35] and RAVDESS [21] datasets, which consist of talking-face video corpus featuring actors and actresses expressing various emotions. Our selection process involves carefully choosing sentences that cover all phonemes within each emotion category. Sentences within each emotion category are then divided into two parts: four common sentences and seven emotion-specific sentences. Further details about the speech corpus are provided in Table 2.3.

3.2 Data Acquisition

Our in-house professional artists meticulously craft animation clips frame by frame, using reference human video clips outlined in the

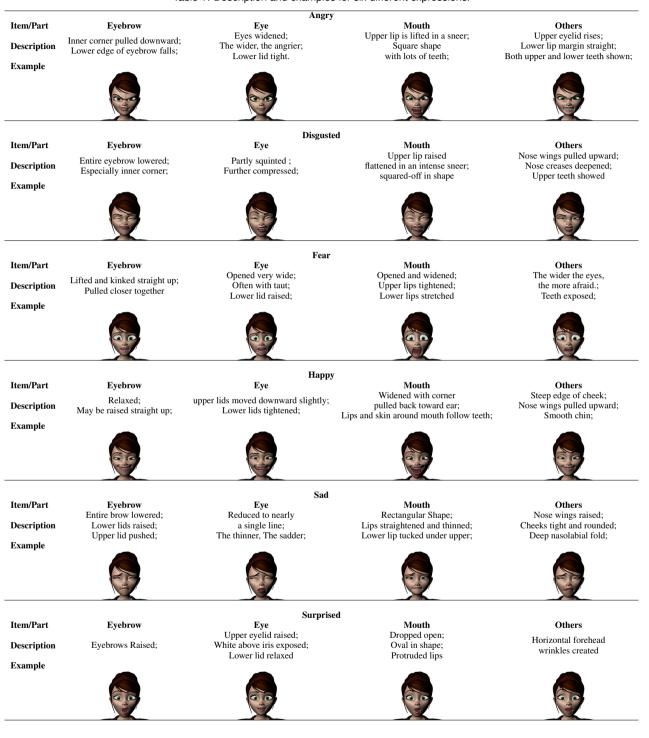


Table 1: Description and examples for six different expressions.

Table 2: Designed speech corpus.

Common sentences read in 7 emotions							
Emotion	NO.	Speech Corpus					
All	1	Kids are talking by the door					
	2	Dogs are sitting by the door					
	3	She had your dark suit in greasy wash water all year					
	4	Don't ask me to carry an oily rag like that					
		Emotion-related sentences					
Emotion	NO.	Speech Corpus					
Angry	1	Right now may not be the best time for business mergers					
	2	You're so preoccupied that you've let your faith grow dim					
	3	Lot of people will roam the streets in costumes and masks and having a ball					
	4	Then he would realize they were really things that only he himself could think					
	1	Please take this dirty table cloth to the cleaners for me					
	2	Young children should avoid exposure to contagious diseases					
Disgust	3	You're not living up to your own principles she told my discouraged people					
	4	Pretty soon a woman came along carrying a folded umbrella as a walking stick					
Fear	1	Call an ambulance for medical assistance					
	2	The fish began to leap frantically on the surface of the small lake					
	3	We will achieve a more vivid sense of what it is by realizing what it is					
	4	This is a problem that goes considerably beyond questions of salary and tenure					
Нарру	1	The eastern coast is a place for pure pleasure and excitement					
	2	By that time perhaps something better can be done					
	3	Obviously the bridal pair has many adjustments to make to their new situation					
	4	His artistic accomplishments guaranteed him entry into any social gathering					
Sad	1	There's no chance now of all of us getting away					
	2	The diagnosis was discouraging however he was not overly worried					
	3	The prospect of cutting back spending is an unpleasant one for any governor					
	4	But the ships are very slow now and we don't get so many sailors any more					
Surprise	1	He ate four extra eggs for breakfast					
	2	I just saw Jim near the new archeological museum					
	3	He further proposed grants of an unspecified sum for experimental Hospitals					
	4	Properly used the present book is an excellent instrument of enlightenment					
Neutral	1						
	1	The best way to learn is to solve extra problems					
	2	As such it was beyond politics and had no need of justification by a message					
	3	Keep your seats boys I just want to put some finishing touches on this thing					
	4	Bridges tunnels and ferries are the most common methods of river crossings					

table 2.3, and analyzing its key movements and expressions. They create a detailed storyboard, rig the character, set keyframes, and use in-betweening for smooth transitions. Special attention is given to replicating facial expressions, following guidance from the book 'The Artist's Complete Guide to Facial Expression.' [12]. Refer to the Table 1 for a detailed breakdown of facial expressions and their features.

4 METHOD

4.1 Overview

We propose a facial animation method, which involves generating precise lip movements and expressions based on the input audio and emotion category. Figure 3 shows an overview of the system, which consists of three essential components. Specifically, we first employ a pre-trained HuBERT model [14] to extract HuBERT features and introduce a Mou Decoder to generate accurate rig parameters related to mouth region. Next, we adopt an Audio Encoder and an Emotion Encoder to extract audio features from MFCC and emotion embedding, respectively. Then the features are combined and fed in to the designed Emo decoder to predict emotional parameters, which are further fused with lip parameters to control the 3D stylized characters' emotions as they speak along with the input audio. Lastly, the vivid animations are produced by rendering process in Maya.

4.2 Architecture

Within the network architecture, there are five sub-networks: a pretrained HuBERT encoder E_h , a mouth decoder D_m , an audio encoder E_a , an emo encoder E_e and a emotion decoder denoted as D_e .

HuBERT Encoder To make full use of the information contained in the audio, we adopt a pre-trained HuBERT model to extract features. Instead of directly taking the final embedding as the subsequent input [37], we predict N hidden layers, which are weighted summed to feed into the Mon Decoder. The obtained HuBERT feature f_h can be represented as:

$$f_h = \sum_{i=1}^{N} (\alpha_i h_i) \quad , \quad \sum_{i=1}^{N} \alpha_i = 1$$
 (1)

where h_i and α_i denote the *i*th hidden layer and corresponding weight.

Mouth Decoder The Mouth Decoder consists of 2-layer 1D convolutional neural network, a 2-layer BiLSTM Network. The former is responsible for downsample the extracted HuBERT feature from 50Hz to 25Hz, while the latter is capable of decoding the feature into meaningful latent representation, which are further to predict the rig parameter sequence of the lip region.

Audio Encoder Considering expression are more correlated to the rhythm and beat instead of phonemes, we extract the Mel-Frequency Cepstral Coefficients (MFCC) [22] aspect from the provided input audio signal, while pairing the video frames and audio signal using a one-second temporal sliding window. Both the audio frame sample rate and video frame rate are set at 25. Subsequently, we apply the audio encoder, which comprises convolutional neural networks (CNN) followed by multi-layer perceptrons (MLP), to process the 28×12 -dimensional audio features as input and obtain the desired audio feature.

Emotion Encoder We first encode the emotion label as a onehot vector e and input it into the emotion encoder. The emotion encoder utilizes a two-layer fully connected (FC) neural network followed by a LeakyReLU activation to map the one-hot vector to an emotion embedding. This embedding is duplicated for each time step.

Emotion Decoder Based on the audio temporal properties, we design the emotion decoder with a long short-term memory (LSTM) network and a fully connected layer to map from the extracted audio feature and emotion embeddings to the rig parameters. The LSTM in our model is composed of three layers with 60 nodes and 100 time steps. In this way, the sequential relationship between audio signals and rig parameters can be better captured.

4.3 Objective Functions

Formulaically, given an audio $a = \{a^{(1)}, \dots, a^{(T)}\}$ and the input emotion condition e, we are able to generate the predicted mouth rig parameters $\hat{y_m} = \{\hat{y_m}^{(1)}, \dots, \hat{y_m}^{(T)}\}$ and expression rig parameters $\hat{y_e} = \{\hat{y_e}^{(1)}, \dots, \hat{y_e}^{(T)}\}$, respectively:

$$\left[\hat{y_m}^{(t)}, h^{(t)}, c^{(t)}\right] = D_m(E_h(a^{(t)}), \hat{y_m}^{(t-1)}, h^{(t-1)}, c^{(t-1)}), \quad (2)$$

$$\left[\hat{y_e}^{(t)}, h^{(t)}, c^{(t)}\right] = D_e(E_a(a^{(t)}), E_e(e), \hat{y_e}^{(t-1)}, h^{(t-1)}, c^{(t-1)}), \quad (3)$$

where $h^{(t)}, c^{(t)}$ represent hidden state and cell state of LSTM unit at time *t* respectively, and *T* refers to the frames of the video. Then, we fuse the predicted parameters to obtain the final results $\hat{y}^{(t)}$:

$$\hat{y}^{(t)} = F(\hat{y_m}^{(t)}, \hat{y_e}^{(t)}), \tag{4}$$

To optimize the network, the L_2 loss function and the Soft-DTW loss [6]¹ are established to define the task. Soft-DTW [7] refers to Soft-Dynamic-Time-Warping, which is a variant of the vanilla Dynamic-Time-Warping (DTW) [31]. It addresses the challenge of non-back-propagatable gradients inherent in vanilla DTW. DTW itself aims to optimize the alignment of sequential data and measures their similarity. Recent studies [4,6,16] have highlighted DTW's superior alignment capabilities, especially with unequal sequence data. Drawing inspiration from these findings, we integrate Soft-DTW

loss into our work to tackle potential synchronization issues between audio and ground-truth rig parameters in our dataset. The prevalence of synchronization challenges in existing datasets, stemming from equipment, transmission, and storage inconsistencies, is amplified in 3D datasets due to animator errors. Therefore, leveraging Soft-DTW loss offers notable advantages in enhancing audio-lip synchronization compared to the conventional MSE loss, which is validated in the following section. Also, we introduce an inter-frame continuity loss [38] to deal with the jitter issue. Given the ground truth rig parameter y, the total loss function \mathcal{L} can be represented as:

$$\mathscr{L} = \mathbb{E}_{a,e,y} \left[(y - \hat{y})^2 + DTW(y, \hat{y}) \right] + \lambda_1 \mathbb{E}_{\hat{y}} \left[\sum_{t=0}^{T-1} \left(\hat{y}^{(t+1)} - \hat{y}^{(t)} \right)^2 \right],$$
(5)

where GT y denotes the Ground Truth (GT) rig parameter, specifically the essential factor guiding our 3D characters to execute the intended movements. Acquired from our constructed dataset, we treat this as the label for our audio-driven animation task. Consequently, we compute the loss by measuring the disparity between the predicted value \hat{y} and the Ground Truth y, employing it to train our network.

5 EVALUATION

5.1 User Study

5.1.1 Participant

We recruited 25 participants from Shanghai Jiao Tong University to participate in all aspects of this study. Twenty participants undertook task 1, while an additional five participants were designated for task 2. The participants had an average age of 22 years, with an age range between 19 and 24; 12 were male. They were unaware of the experiment's objectives.

5.1.2 Material

Task 1 To assess our dataset, we generated animation clips using the 3D facial rig included in the dataset, accompanied by the corresponding rig parameters. We divided our dataset into four group (see No. in Table 2.3).

Task 2 To evaluate our method, we randomly selected 75% of dataset to train our model & EVP [26], and used the rest of dataset as ground true. Then, we run our method & EVP method to create 7 animation clips for primary character expression, and apply the Multiple Character Adaptation network [26] transfer the expression on different 5 stylized characters.

5.1.3 Design

Task 1 The experiment involved 7 characters (Human, Mery, Bonnie, Ray, Malcolm, Rose & Miosha) \times 7 emotions (Neutral, Anger, Sadness, Fear, Disgust, Happiness, & Surprise) \times 2 sentences (Common sentences vs. Emotion-related sentences) \times 4 groups of datasets in a mixed design. It incorporated a between-subject design for tracking methods, while maintaining a within-subject design for characters, emotions, and tracking methods.

Every participant engaged in 98 trials, assessing human expression and the 6 character expression: $7 \times (7 \text{ emotions } \times 2 \text{ types} \text{ of sentence}) = 98 \text{ trials}$. Consequently, the total number of trials amounted to 1960.

Task 2 The experiment utilized 6 characters (Mery, Bonnie, Ray, Malcolm, Rose & Miosha) \times 7 emotions (Neutral, Anger, Sadness, Fear, Disgust, Happiness, & Surprise) \times 3 methods in a within-subject design.

Each participant engaged in 126 trials, assessing both the generated primary character expression and the expression transfer results on 5 different stylized characters: $6 \times (7 \text{ emotions} \times 3 \text{ capturing} \text{ methods}) = 126 \text{ trials}$. The total number of trials amounted to 630.

To prevent fatigue or carry-over effects, video clips were presented to the participants in a random order.

¹Implementation refers to https://github.com/Moon0316/T2A

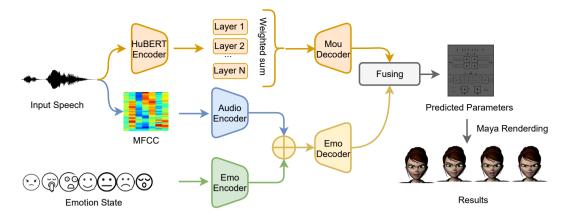


Figure 3: The overview of our system.

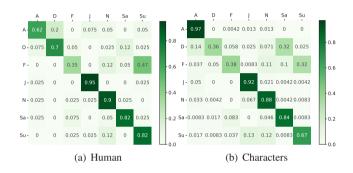


Figure 4: Confusion matrix for perceived expression recognition (%) for seven expression classes. A = anger, D = disgust, F = fear, J = joy, N = neutral, Sa = sadness, Su = surprise.

5.1.4 Procedure

Participants first received an information sheet and were asked to sign a corresponding consent form. They were then directed to watch an animation clip and respond to four questions:

- "Which expression did the character depict?" Participants selected one of the words: Neutral, Anger, Sadness, Fear, Disgust, Happiness, Surprise, or Other.
- "How intense was the indicated emotion depicted by the character?" Participants rated the intensity on a scale from 1 to 7, where 1 represented "Not at all," and 7 represented "Extremely."
- "Whether the lip motion syncs with the speech?" Participants rated lip sync qualities on a scale from 1 to 7, where 1 indicated no synchronization at all and 7 indicated extremely well-synchronized.
- "How natural was the character overall?" Participants rated attractiveness on a scale from 1 to 7, where 1 represented "Not at all," and 7 represented "Extremely."

Each participant completed one practice trial, during which they could ask questions, before proceeding to the measured trials.

Participants were remunerated with 50RMB, and the entire experiment lasted approximately 30 minutes. The research protocol received approval from the Shanghai Jiao Tong University Research Ethics Committee.

5.1.5 Results on datasets

For the statistical analysis, we performed separate repeated measures Analyses of Variances (ANOVAs) for videos, examining results related to recognition, intensity, synchronization, and naturalness. There were no outliers, and the data exhibited normal distribution for each condition, as confirmed by boxplot and the Shapiro–Wilk test (p > 0.05), respectively. We conducted Mauchly's test to validate the sphericity of the data, and whenever it was significant, we present results with the Greenhouse-Geisser correction applied and marked with an asterisk "*". Post hoc tests were carried out using the Bonferroni test for mean comparisons.

Recognition For emotion recognition, responses were converted into scores of "1" (correct) or "0" (incorrect) and then averaged across repetitions of stimuli.

Figure 5(a) shows that anger (M = .921, SE = .014), joy (M = .925, SE = .019), neutral (M = .886, SE = .027), and sadness (M = .836, SE = .034) show high accuracy, whereas disgust (M = .407, SE = .041) and fear (M = .375, SE = .05) are very difficult for users to perceive. We also observed the character expression recognition accuracy could occasionally be higher than humans, this might be because the characters have simpler geometry and stylization can make the expressions relatively easier to perceive.

We compared average scores obtained for 7 emotions across 7 characters. We found the main effect of the character was significant, F(6,114) = 3.215, p = .006, and the characters × emotions interaction was also significant, F(36,684) = 3.957, p < .001. This indicates the recognition score for different characters present differently for different emotions.

Our initial results on expression recognition shows that the main effect of emotions was significant, $F(3.79, 72.003) = 53.139, p < .001^*$. Hence, we examined participants' ratings for seven expression classes. Figure 4 illustrates the confusion matrix for perceived expression recognition for each expression class. In each sub-figure, for a given row (e.g., anger), the columns depict the percentage (averaged over all perceived human/character anger expressions) of participants agreeing on the corresponding expression classes.

Intensity Intensity ratings for our characters were high in general, which is expected for exaggerated cartoon animation. Figure 5(b) shows the mean intensity ratings for 7 emotions across 7 characters. The average score over all characters for neutral (M = 3.461, SE = .398) is significantly lower than the average score for the rest of emotions.

We found the main effect of character, the main effect of emotion, and characters × emotions interaction were all significant, $F(1.963, 37.288) = 8.515, p < .001^*, F(1.874, 35.606) = 27.03, p < .001^*$, and F(36, 684) = 3.386, p < .001, respectively.

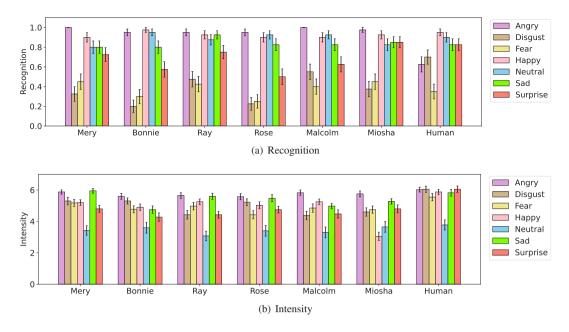


Figure 5: Results on datasets

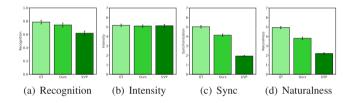


Figure 6: Results on our methods

This indicates the intensity score for different characters present differently for different emotions.

Synchronization & Naturalness We look at the rating on synchronization & naturalness for 7 emotions across 7 characters conditions. However, no statistically significant effects were found, in terms of characters, emotions and the characters \times emotions interaction, thus we did not include the figure results for synchronization & naturalness.

5.1.6 Results on our methods

Recognition Figure 6(a) shows the comparison of average recognition scores obtained for three generation methods across six stylized characters. The average score over all characters for GT (M = .786, SE = .046) and our methods (M = .743, SE = .033) are slightly higher than the average score for the EVP (M = .619, SE = .03). We found the main effect of the generation method was significant, F(2,8) = 5.056, p = .038. However, Bonferroni post-hoc comparisons did not find any significant effect among these conditions.

Intensity Figure 6(b) shows the comparison of average intensity scores obtained for three generation methods across six stylized characters. The average score over all characters for GT (M = 5.171, SE = .603), our methods (M = 5.09, SE = .62), and EVP (M = 5.133, SE = .668), respectively. Results revealed the main

effect of methods on intensity scores was not statistically significant, $F(1.021, 4.085) = .056, p = .83^*$.

Synchronization Figure 6(c) shows the mean synchronization ratings for three generation methods across six characters. The average score over all characters for GT (M = 5.024, SE = .703), and our methods (M = 4.133, SE = .633) are significantly higher than the average score for EVP (M = 1.929, SE = .347).

The main effect of the generation method was significant, F(2,8) = 16.531, p = .001. Bonferroni post-hoc comparisons indicated the mean synchronization ratings for GT and our methods are significantly higher than EVP, p = .038 and p = .023, respectively.

Naturalness Figure 6(d) shows the mean naturalness ratings for three generation methods across six characters. The average score over all characters for GT (M = 4.983, SE = .681), and our methods (M = 3.805, SE = .672) are significantly higher than the average score for EVP (M = 2.186, SE = .411).

The main effect of the generation method was significant, F(2,22) = 15.077, p = .002. Bonferroni post-hoc comparisons indicated the mean naturalness ratings for GT and our methods are significantly higher than EVP, p = .035 and p = .028, respectively.

5.2 Comparison & Ablation Study

We introduce two new metric, facial rig parameter distance (F-RPD) and mouth rig parameter distance (M-RPD), which calculates the distance between facial and mouth rig parameters generated by different methods (EVP, w/o Soft-DTW, w/o Emo Encoder and Ours) and ground truth (GT). EVP [26] tackles the same task with our method. For ablation study, we replace Soft-DTW loss with MSE loss, denoted as w/o Soft-DTW. w/o Emo Encoder refers to our framework without Emo Encoder, which generates neutral talking faces without any expressions. The results in Table 3 illustrate the Soft-DTW loss and the emotion branch in our framework plays a great role in performing lip-sync and expressions, respectively.

We select some frames from the videos (left: *sad* emotion; right: *surprised* emotion) generated by ground-truth (GT), EVP [26], w/o emo encoder(ablation study) and our method. Specifically, EVP predicts wrong lip motions and w/o emo encoder fails to generate

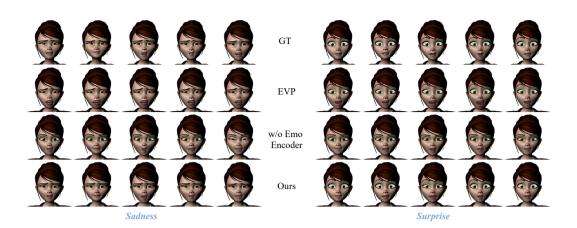


Figure 7: Sampled frames from ground-truth (GT), EVP [26], w/o emo encoder and our method.

Table 3: Quantitative results for comparison & ablation study.

Metric/Method	EVP [26]	w/o Soft-DTW	w/o Emo Encoder	Ours
F-RPD M-RPD	0.179 0.094	0.057	0.089 0.037	0.014
	0.094	0.029	0.037	0.005

vivid expressions. Our method not only produces accurate mouth shapes, but also presents the similar expressions as GT.

6 DISCUSSION

6.1 Audio, Video & Text

Talking avatar generation is a typical multi-modal task involving the creation of videos featuring characters speaking, driven by an audio clip, a text script or a video sequence. In this paper, we introduce an audio-visual dataset and present a system tailored for generating talking avatars driven by audio input. Importantly, our system can be easily adapted for text-driven or video-driven scenarios. On the one hand, the prosperous text-to-speech (TTS) [9,28] systems are capable of synthesizing high-quality audio from text, which equips our method with the necessary audio inputs for processing. On the other hand, we aim to build an avatar-human dataset that establishes a direct one-to-one relationship between avatars and real humans, enabling us excel in the generation of video-driven avatars in the future.

6.2 Multiple Characters & Human Faces Adaptation

To generalize the character's expressions, we used the idea discussed in previous work. The facial expressions are governed by distinct, independent action units. We segment the character's face into five parts: brow, eye, mouth, cheek, and nose. We utilize rig parameters as feature vectors and employ a MLP network for each segment, to transfer facial expression from primary to secondary character. Additionally, our current pipeline is tailored for stylized characters featuring exaggerated and artistic expressions. As discussed in section 2.2, numerous audio-driven methods have been developed specifically for animating human faces. Our pipeline can easily adapt to human faces by incorporating an emotional human faces dataset.

6.3 Application, Limitation & Future work

Our audio-driven approach excels at generating emotionally expressive avatars, fostering direct interaction among VR users equipped

with head-mounted displays. Our method generates rig parameters for animating 3D characters. These rig parameters can be easily applied to avatars in Unity, allowing users to perceive the avatars as alive inside VR. The audio-based approach addresses a primary challenge in VR communication, which arises from the majority of the face being obscured by the HMD. Moreover, our method proves particularly beneficial in VR teleconferencing scenarios due to low bandwidth requirements. It only necessitates the transfer of the character's 3D rig parameters from the server, allowing direct animation at the client side, as opposed to transferring videos. There are a couple of potential avenues for the next steps. Our initial user study validated the effectiveness for our dataset and our method. We plan to include more participant from diverse background (e.g., geographical regions) to explore user's expression recognition for stylized characters. Additionally, it would be intriguing to introduce the concept of a universal primary character rig that is powerful enough to generate a full range of expressions and can be easily adapted to unconventional character designs, such as one-eyed or fantastical characters.

7 CONCLUSION

Representing characters with clear, unambiguous expressions in the task of talking head generation has often been overlooked in previous works, primarily due to the lack of a suitable emotional audio-visual dataset for 3D rigs. Our contribution addresses this gap by providing a novel, high-quality Emotional Talking Avatar Dataset that offers rich and accurate affective visual and audio information with great detail. We then developed a novel approach to facial animation combines input audio and emotional cues to achieve precise lip movements and expressive expressions for stylized characters. Incorporating the built Emotional Talking Avatar Dataset, our method outperforms the SOTA emotional talking face method by applying the Soft-DTW loss, the pre-trained HuBERT feature extractor and the emotion branch. We believe our new dataset and the new method would benefit the community of expressive avatar animation and contribute to applications in diverse fields, including social VR experiences, teleconferencing, visual games, and storytelling.

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